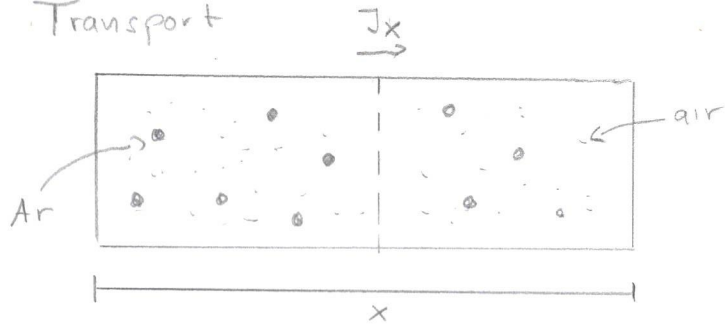


Transport



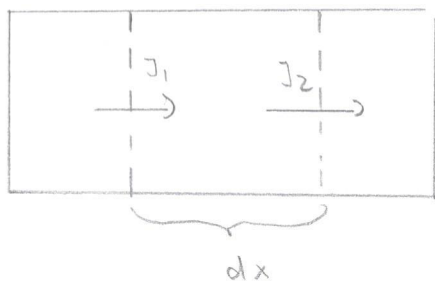
flux $J_x = -D \frac{\partial c}{\partial x}$ } concentration gradient

↙ diffusion coefficient

$\left[\frac{\#}{m^2 s} \right] \quad \left[\frac{m^2}{s} \right]$

Fick's first law

concentration c is a function of time and location $c(x, t)$



$$\frac{\partial c(x, t)}{\partial t} = - \frac{\overbrace{(J_2 - J_1) A \Delta t}^{\text{flux divergence}}}{\underbrace{A \Delta x}_{\text{Volume}}}$$

$$\frac{\partial c(x, t)}{\partial t} = - \frac{\partial J}{\partial x} = \frac{\partial}{\partial x} D \frac{\partial c}{\partial x}$$

3D: $c(x, y, z, t)$

$$\frac{\partial c}{\partial t} - \frac{\partial}{\partial x} D \frac{\partial c}{\partial x} - \frac{\partial}{\partial y} D \frac{\partial c}{\partial y} - \frac{\partial}{\partial z} D \frac{\partial c}{\partial z} = 0$$

$$\frac{\partial c}{\partial t} - \nabla \cdot (D \nabla c) = 0$$

$$\frac{\partial c}{\partial t} - \nabla \cdot (D \nabla c) = S \quad \begin{matrix} \text{internal} \\ \text{sources or sinks} \end{matrix}$$

Advection: transport by flow

$$Dc(x,y,z,t) = \frac{\partial c}{\partial x} dx + \frac{\partial c}{\partial y} dy + \frac{\partial c}{\partial z} dz + \frac{\partial c}{\partial t} dt$$

↑

total derivative

$$\frac{Dc}{dt} = \frac{\partial c}{\partial x} \underbrace{\frac{dx}{dt}}_{u_x} + \frac{\partial c}{\partial y} \underbrace{\frac{dy}{dt}}_{u_y} + \frac{\partial c}{\partial z} \underbrace{\frac{dz}{dt}}_{u_z} + \frac{\partial c}{\partial t}$$

$$\vec{u} = [u_x, u_y, u_z]$$

flow vector

$$\underbrace{(\vec{u} \cdot \nabla)}_{\text{advection operator}} = [u_x, u_y, u_z] \cdot \left[\frac{\partial}{\partial x}, \frac{\partial}{\partial y}, \frac{\partial}{\partial z} \right]$$

$$\frac{Dc}{dt} = \frac{\partial c}{\partial t} + (\vec{u} \cdot \nabla) c$$

more general

$$= \frac{\partial c}{\partial t} + \underbrace{\nabla \cdot (\vec{u} c)}_{\begin{aligned} &\vec{u} \cdot (\nabla c) + (\nabla c) \cdot \vec{u} \\ &(\vec{u} \cdot \nabla) c + (\nabla \cdot \vec{u}) c \end{aligned}}$$

"product rule"

$\nabla \cdot \vec{u} = 0$ for incompressible flow

advection - diffusion equation

$$\underbrace{\frac{\partial c}{\partial t}}_{\text{local change}} - \underbrace{\nabla \cdot (D \nabla c)}_{\text{diffusion}} + \underbrace{\nabla \cdot (c \vec{u})}_{\text{advection}} = \underbrace{S}_{\text{sources - sinks}}$$

Heat equation

$$\rho c_p \frac{\partial T}{\partial t} - \nabla \cdot (k \nabla T) + \nabla \cdot (c \vec{u} T) = \underbrace{q}_{\text{heat added / subtracted to unit volume}}$$

$\left[\frac{\text{kg}}{\text{m}^3} \right] \left[\frac{\text{J}}{\text{kg K}} \right] \left[\frac{\text{K}}{\text{s}} \right]$
 $\frac{\text{J}}{\text{s m}^3}$

$\frac{\text{J}}{\text{s m}^3}$

Basic 1D heat equation

- no advection ($\nabla \cdot (\vec{u} T) = 0$)
- no sources / sinks ($q = 0$)
- 1 dimension ($\frac{\partial T}{\partial y} = 0$ $\frac{\partial T}{\partial z} = 0$)
- $k, \rho, c_p = \text{constant}$

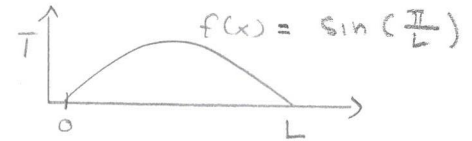
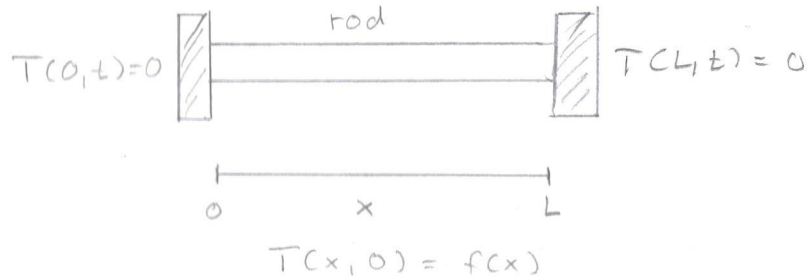
$$\rho c_p \frac{\partial T}{\partial t} = \frac{\partial}{\partial x} k \frac{\partial T}{\partial x}$$

$$\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2}$$

$$\alpha = \frac{k}{\rho c_p} \quad \left[\frac{\text{m}^2}{\text{s}} \right]$$

"thermal diffusivity"

Solving PDEs: Separation of variables



PDE: $\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2}$

Problem: seek $T(x,t)$ that satisfies
initial and boundary conditions

Approach: Separation of variables (functions)

- works for linear + homogeneous systems

- assume that solutions will be a product of two functions each function only with one variable

$$T(x, t) = A(x) B(t)$$

- apply proposed solution to PDE

$$\frac{\partial(A(x)B(t))}{\partial t} = \alpha \frac{\partial^2(A(x)B(t))}{\partial x^2}$$

$$A \frac{dB}{dt} = \alpha B \frac{d^2A}{dx^2}$$

- separate functions

$$\underbrace{\frac{1}{\alpha B} \frac{dB}{dB}}_{\text{function of } t \text{ only}} = \underbrace{\frac{1}{A} \frac{d^2A}{dx^2}}_{\text{function of } x \text{ only}} = -m$$

function of
t only

function
of x only

↑ makes solution
easier later

must be equal for all t
and x values

⇒ must equal to a
const.

time ODE

$$\frac{dB}{dt} = -\alpha m B$$

Space ODE

$$\frac{d^2 A}{dx^2} = -m A$$

→ two ordinary diff Eq.

- solve space ODE

$$T(x, t) = A(x) B(t)$$

$$T(0, t) = A(0) B(t)$$

$$T(L, t) = A(L) B(t)$$

} Boundary conditions $A(0) = A(L) = 0$

trivial solution: $B(t) = 0$ for all $t \Rightarrow T(x, t) = 0$

$\Rightarrow A(0) = 0$ and $A(L) = 0$ must hold

→ found IVP for space ODE

- Solve space ODE

$$\frac{d^2 A}{dx^2} + m A = 0$$

$$A(0) = 0$$

$$A(L) = 0$$

problem: we do not know $m \Rightarrow$ try cases

$$m = 0$$

$$\frac{d^2 A}{dx^2} = 0$$

$\Rightarrow$

$$A(x) = c_1 + c_2 x$$

$$A(0) = 0 \Rightarrow c_1 = 0$$

$$A(L) = 0 \Rightarrow c_2 L = 0 \Rightarrow c_2 = 0$$

} trivial solution

$$m \neq 0 \quad \frac{d^2 A}{dx^2} + m A = 0$$

characteristic equation

$$\lambda^2 + m = 0 \quad \Rightarrow \quad \lambda_{1,2} = \pm \sqrt{-m}$$

$$\text{solution: } A(x) = c_1 \exp(\lambda_1 x) + c_2 \exp(\lambda_2 x)$$

$$m < 0: \quad A(0) = c_1 + c_2 = 0 \quad \Rightarrow \quad c_1 = -c_2$$

$$A(L) = c_1 \exp(\lambda_1 L) + c_2 \exp(\lambda_2 L) = 0$$

$$\Rightarrow \quad \frac{c_1}{c_2} \exp(\lambda_1 L) = -\exp(\lambda_2 L)$$

$$\Rightarrow \quad -\exp(\lambda_1 L) = -\exp(\lambda_2 L)$$

$$\Rightarrow \quad \lambda_1 = \lambda_2 \quad \Rightarrow \quad \text{only possible for } m = 0$$

$$m > 0$$

$$\Rightarrow z_{1,2} = \pm \sqrt{m} i = 0 \pm \sqrt{m} i$$

$$a \pm b i$$

$$A(x) = \exp(ax) (c_1 \cos(bx) + c_2 \sin(bx))$$

$$A(x) = c_1 \cos(\sqrt{m} x) + c_2 \sin(\sqrt{m} x)$$

$$A(0) = 0 \Rightarrow c_1 = 0$$

$$A(L) = 0 \Rightarrow c_2 \sin(\sqrt{m} L) = 0$$

$$\text{if } c_2 \neq 0 \Rightarrow \sin(\sqrt{m} L) = 0$$

infinite solutions: $\sin(x) = 0$ for $0, \pi, 2\pi, \dots, n\pi$

$$\sqrt{m} L = n\pi \Rightarrow m_n = \left(\frac{n\pi}{L}\right)^2 \quad n=1, 2, \dots$$

$$A_n(x) = c_2 \sin\left(\frac{n\pi}{L} x\right)$$

↑
still unknown

- Solve time equation

$$\frac{dB}{dt} = -\alpha m_n B$$

$$m_n > 0 = \left(\frac{n\pi}{L}\right)^2$$

$$B(t) = C_1 \exp\left(-\alpha \left(\frac{n\pi}{L}\right)^2 t\right)$$

- PDE solution

$$T(x, t) = A(x) B(t)$$

$$T(x, t) = c \sin\left(\frac{n\pi}{L} x\right) \exp\left(-\alpha \left(\frac{n\pi}{L}\right)^2 t\right)$$

$$\omega = \frac{n\pi}{L}$$

$$T(x, t) = c \sin(\omega x) \exp(-\alpha \omega^2 t)$$

IVP

$$T(x, 0) = f(x) = c \sin(\omega x)$$

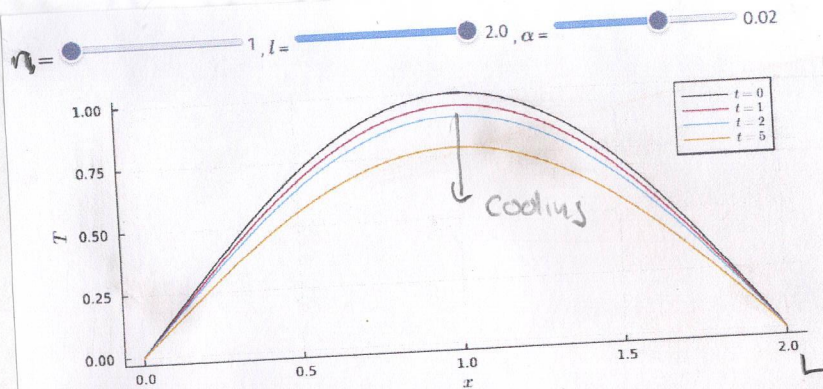
$$= c \sin\left(\frac{n\pi}{L} x\right)$$

$$\text{original } f(x) = \sin\left(\frac{\pi}{L} x\right)$$

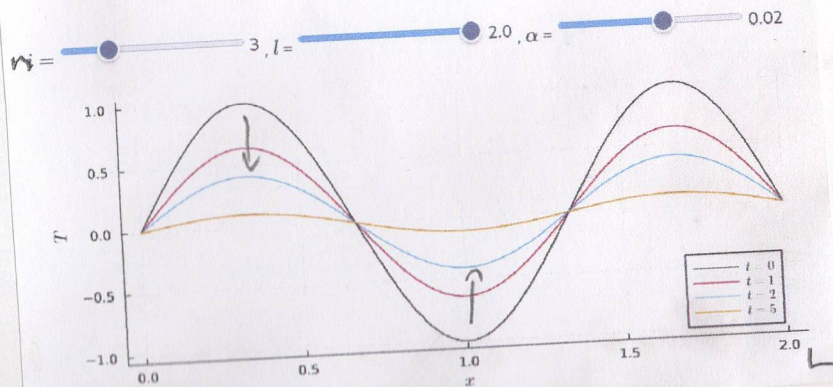
$$n=1$$

$$\Rightarrow c = 1$$

$$T(x, t) = \sin\left(\frac{\pi}{L} x\right) \exp\left(-\alpha \left(\frac{\pi}{L}\right)^2 t\right)$$



$$\alpha \uparrow \Rightarrow \frac{\partial T}{\partial t} \uparrow$$



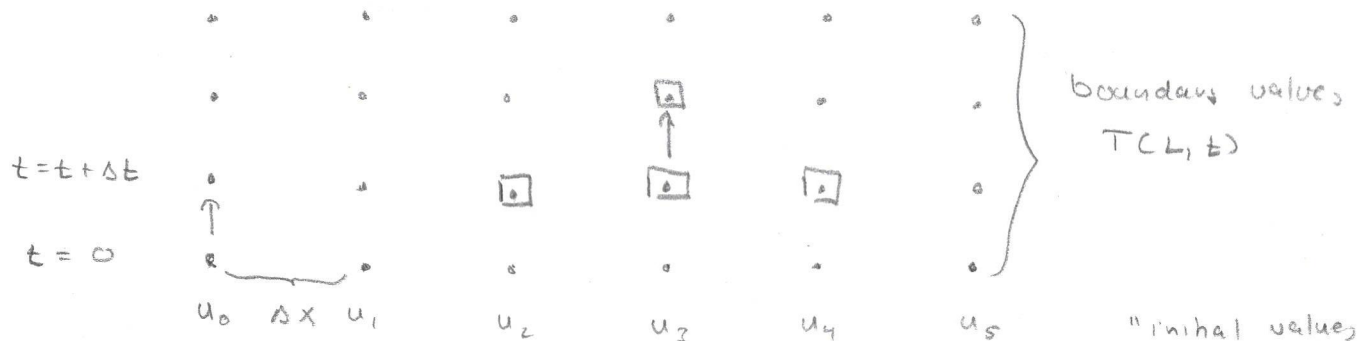
$$T(x, t) = \sin\left(\frac{3\pi}{L}x\right) \exp\left(-\alpha\left(\frac{3\pi}{L}\right)^2 t\right)$$

Numerical Solution to PDEs

$$\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2}$$

"Method of Lines" : RHS as finite difference approximation

$$f''(x) = \frac{f(x+h) - 2f(x) + f(x-h)}{h^2}$$



$$du_0 = 0 = u_0(t+\Delta t)$$

$$du_1 = u_1(t+\Delta t) = \alpha \frac{u_2 - 2u_1 + u_0}{\Delta x^2} = \frac{\alpha}{\Delta x^2} (u_2 - 2u_1 + u_0)$$

⋮

$$d\vec{u} = \begin{bmatrix} du_0 \\ du_1 \\ du_2 \\ du_3 \\ du_4 \\ du_5 \end{bmatrix} = \frac{\alpha}{\Delta x^2} \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & -2 & 1 & 0 & 0 & 0 \\ 0 & 1 & -2 & 1 & 0 & 0 \\ 0 & 0 & 1 & -2 & 1 & 0 \\ 0 & 0 & 0 & 1 & -2 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} u_0 \\ u_1 \\ u_2 \\ u_3 \\ u_4 \\ u_5 \end{bmatrix}$$

$$d\vec{u} = \frac{\alpha}{\Delta x^2} A \vec{u} \quad \Delta x^2 = \frac{L}{n-1}$$

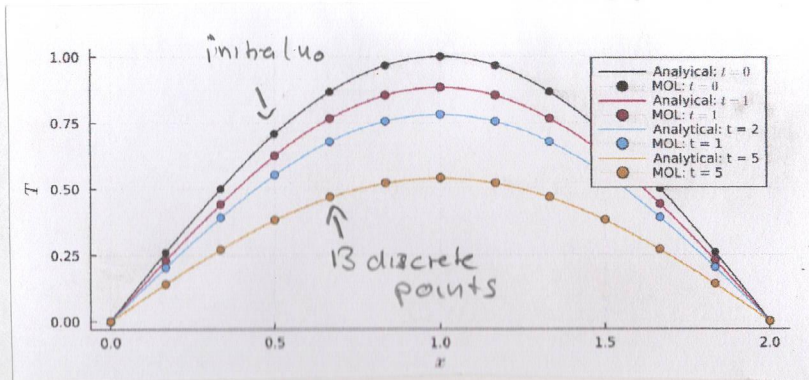
$$A \in \mathbb{R}^{n \times n}$$

System of first order ODEs $\Rightarrow$ use ODE solver

$$\left. \begin{array}{l} du_0 = 0 \\ du_{n-1} = 0 \end{array} \right\} \text{Dirichlet Boundary Condition}$$

- u_0, u_{n-1}
- can take on other values than zero
 - picked zero to compare to analytical solution

Numerical Solution



function $f(u, p, t)$

$$\alpha = p[1]$$

$$\Delta x = p[2]$$

$$A = p[3]$$

$$du = \frac{\alpha}{\Delta x^2} A u$$

return du

end

n is length of u

and A is size (n, n)

Other Boundary Conditions



Dirichlet: fixed value

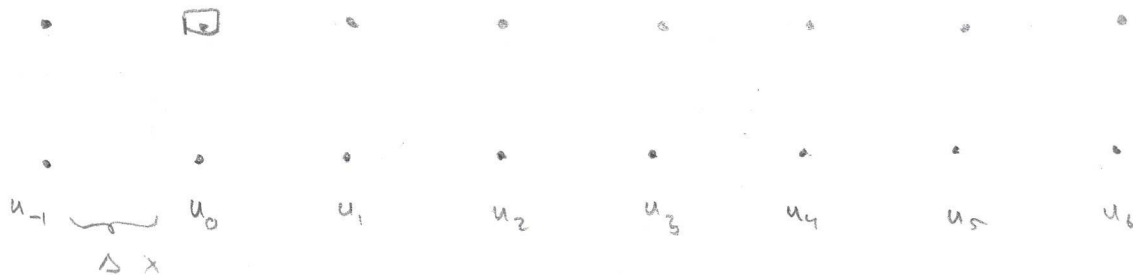
$$\Rightarrow \frac{du_0}{dt} = \frac{du_L}{dt} = 0$$

Neumann: fixed gradient / flux

$$\frac{du_0}{dx} = \frac{du_L}{dx} = C$$

↑
constant

often $C=0$: zero flux $\Rightarrow$ "adiabatic"



$$\frac{u_1 - u_{-1}}{2\Delta x} = C \quad \Rightarrow \quad u_{-1} = u_1 - 2\Delta x C$$

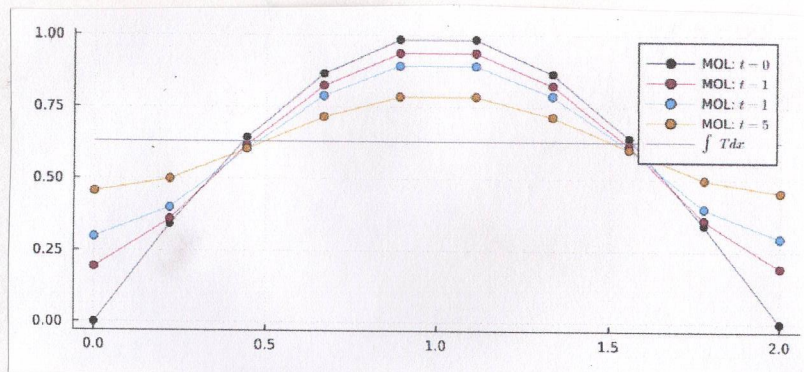
$$\partial_t u_0 = u(t + \Delta t) = \alpha \frac{u_1 - 2u_0 + u_{-1}}{\Delta x^2} = \frac{\alpha}{\Delta x^2} (u_1 - 2u_0 + u_{-1} - 2\Delta x C)$$

for $c=0$

$$du_0 = \frac{\Delta}{\Delta x^2} (2u_1 - 2u_0)$$

$$A = \begin{bmatrix} -2 & 2 & 0 & 0 & \dots & 0 \\ 1 & -2 & 1 & 0 & \dots & 0 \\ 0 & 1 & -2 & 1 & 0 & \dots & 0 \\ & & \ddots & \ddots & \ddots & \ddots & \\ 0 & 0 & \dots & \dots & -2 & 2 \end{bmatrix}$$

$$d\vec{u} = \frac{\Delta}{\Delta x^2} A \vec{u}$$



Numerical Solution Stability

Integration through Euler's Method

$u_i^j \leftarrow \text{time}$
 $u_i^j \leftarrow \text{space}$

$$du = \frac{u_i^{j+1} - u_i^j}{\Delta t} = \alpha \frac{u_{i+1}^j - 2u_i^j + u_{i-1}^j}{\Delta x^2}$$

- could use this to get u_i^{j+1}

system is stable if $\frac{2\alpha\Delta t}{\Delta x^2} \leq 1$

"CFL condition"

(Courant - Friedrich - Lewy)

$\Rightarrow \Delta t$ must be sufficiently small

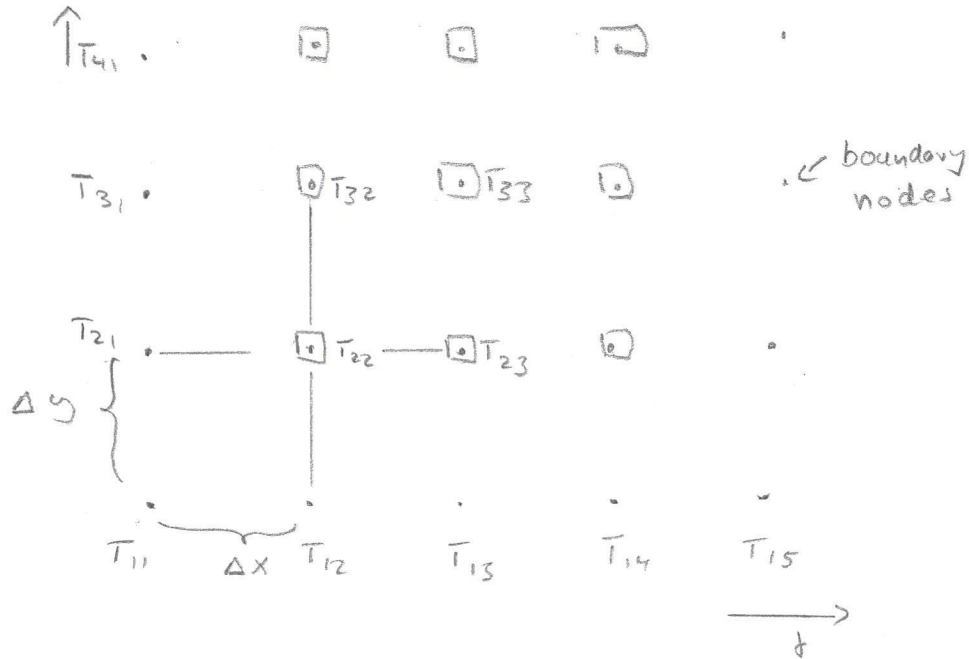
note $\tau_{\text{cond}} = \frac{\Delta x^2}{\alpha}$ time scale of conduction

$$\Rightarrow \Delta t < \frac{1}{2} \tau_{\text{cond}}$$

$\Rightarrow$ may need small Δt and solution is slow

2D case

$$\frac{\partial T}{\partial t} = \alpha \left(\frac{\partial^2 T}{\partial x^2} + \frac{\partial^2 T}{\partial y^2} \right)$$



$$\frac{\partial T_{i,j}}{\partial t} = \alpha \frac{T_{i,j+1} - 2T_{i,j} + T_{i,j-1}}{\Delta x^2} + \alpha \frac{T_{i+1,j} - 2T_{i,j} + T_{i-1,j}}{\Delta y^2}$$

Puff Dispersion

$$\frac{\partial c}{\partial t} = D \frac{\partial^2 c}{\partial x^2}$$

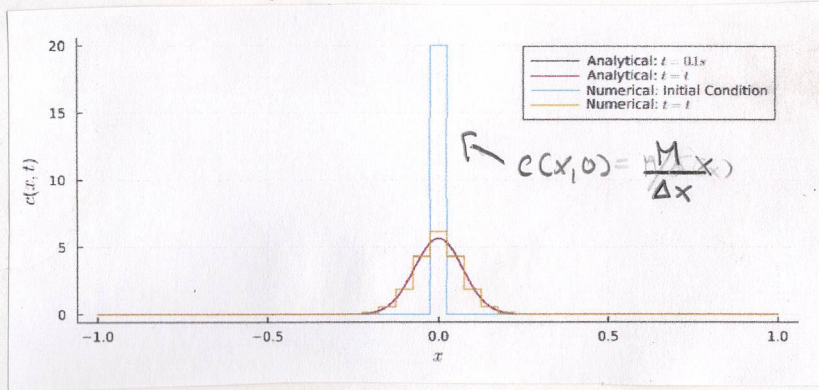
$$C(x, 0) = M \delta(x)$$

$$c(x, t) \rightarrow 0 \quad x \rightarrow \infty$$

Solution identical to heat problem

$$\int_{-\infty}^{\infty} \delta(x) dx = 1$$

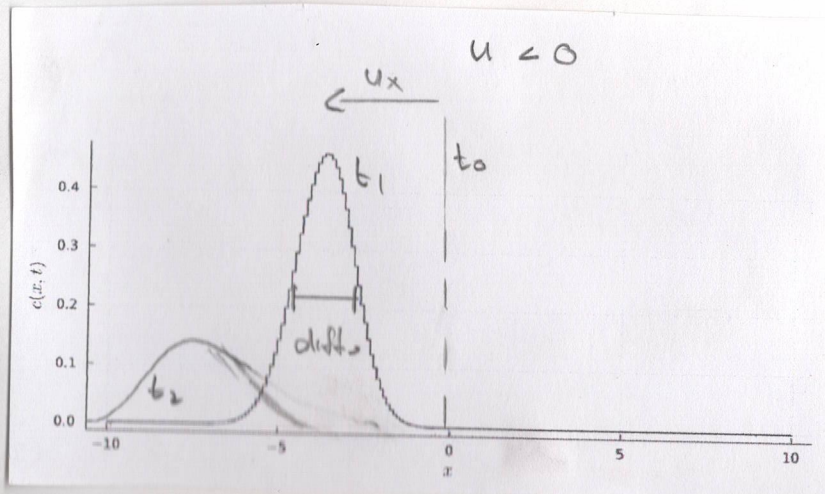
$$C(x, t) = \frac{M}{\sqrt{4\pi Dt}} \exp\left(-\frac{x^2}{4Dt}\right)$$



Puff Dispersion + Advection

$$\frac{\partial c}{\partial t} = D \frac{\partial^2 c}{\partial x^2} - u_x \frac{\partial c}{\partial x}$$

$$\text{MOL: } \frac{\partial c_i}{\partial t} = D \left(\frac{c_{i+1} - 2c_i + c_{i-1}}{\Delta x^2} \right) - u_x \left(\frac{c_{i+1} - c_{i-1}}{2\Delta x} \right) \quad \text{Forward time centered difference (FTSC)}$$



- even for good CFL condition solution will develop oscillations
- need more sophisticated scheme for advection problem
 - upwind scheme / Fromm's method
 - better to solve c_i through loop instead of ODE Solver